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UTILITY PATENT APPLICATION **TRANSMITTAL**

Attorney Docket No. First Named Inventor or Application Identifier David Hoyle, et al. Microprocessor Having a Set of Byte Intermingling Instructions

(Only for new nonprovisional applications under 37 CFR 1.53(b)) Express Mail Label No EL547742295

APPLICATION	ON ELEMENTS		ADDRESS TO: Assistant Commissioner for Patents Box Patent Application			
See MPEP Chapter 600 concer	ning utility patent application cont	ents			Washington, DC 20	
1. X *Fee Transmittal Form (Submit an original, and a	(e.g., PTO/SB/17) duplicate for fee processing)		6.		Microfiche Computer Program (A	opendix)
2. Specification (preferred arrangement)		43	<i>1</i> 7.		eotide and/or Amino Acid Sequence plicable, all necessary)	Submission
 Descriptive title of the Cross References to 				a.	Computer Readable 0	Сору
 Statement Regarding Reference to Microfic 	·			b.	Paper Copy (identical	to computer copy)
 Background of the In Brief Summary of the 				c.	Statement verifying id	entical of above copies
 Brief Description of the Description 	ne Drawings (if filed)			ACC	OMPANYING APPLICA	TION PARTS
Claim(s)Abstract of the Disclo	sure		8.		Assignment Papers (cover sheet	& Documents(s))
3. Name of the Drawing(s) (35 USC d	113) [Total Sheets	14	J 9		37 CFR §3.73(b) Statement (when there is an assignee)	Power of Attorney
4. Oath or Declaration	[Total Pages	X	<i>]</i> 10.		English Translation Document (if	i
a. Newly Execute	d (original or copy)		11.	X	Information Disclosure Statement (IDS)/PTO-1449	Copies of IDS Citations
	Copy from a prior application (37 CFR §1 63(d)) (for continuation/divisional with Box 17 completed)		12.		Preliminary Amendment	
[Note	[Note Box 5 below]			13. Return Receipt Postcard (MPEP 503) (Should be specifically itemized)		
I. Sign nam	DELETION OF INVENTOR(S) Signed statement attached deleting inventor(s) named in the prior application, see 37 CFR §1.63(d)(2) and 1 33(b)				Statement(s) Status s (PTO/SB/09-12) Certified Copy of Priority Docume	ent filed in prior application till proper and desired ent(s)
The entire disclosure of the oath or declaration	Incorporation By Reference (useable if Box 4b is checked) The entire disclosure of the prior application, from which a copy of the oath or declaration is supplied under Box 4b, is considered as being part of the disclosure of the accompanying application and is					
hereby incorporated by	reference therein		whe	re one ha	nent is required to be entitled to pay small as been filed in a prior application and is	being relied upon
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X Customer Number or Bar Code Label 23494 or Correspondence address below (Insert Customer No. or Attach bar code label here)						
NAME Gerald E.	·					
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COUNTRY	STATE				ZIP CODE FAX	972-917-4418
Name (Print/Type)	Gerald E. Laws	972-917	-JZ01	Reg	gistration No. (Attorney/Agent)	39,268
Signature			zece	1	Date	

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Complete If Known **FEE TRANSMITTAL** Application Number Patent fees are subject to annual revision on October 1. October 31, 2000 Filing Date These are the fees effective October 1, 1997 First Named Inventor David Hoyle, et al. Small Entity payments must be supported by a small entity statement, otherwise large entity fees must be paid. See Forms PTO/SB/09-12 express Mailing Label No.: EL547742295 Examiner Name Group / Art Unit Express Mailing Label No.: TI-30561 Attorney Docket No. TOTAL AMOUNT OF PAYMENT

METHOD OF PAYMENT FEE CALCULATION (continued)						
	3.				CALCULATION (continued)	
Deposit Account,					. FEES	
Deposit Account Number	20-0668	Large Fee	Entity Fee	Small Fee	Entity Fee	
Number		Code	(\$)	Code	(\$)	Fee Description Fee Paid
Deposit Account Name Texas	Instruments Incorporated	105 127	130 50	205 227	65 25	Surcharge - late filing fee Surcharge - late provisional filing fee or cover sheet
Charge any additional fee required or credit any overpayment	Charge all indicated fees and any additional fee required or credit any overpayment	139	130	139	130	Non-English specification
	1 - 1 - 111	147	2,520	147	2,520	For filing a request for reexamination
2. Payment Enclos		112	920*	112	920*	Requesting publication of SIR prior to Examiner action
Check	Money Other Order	113	1,840*	113	1,840*	Requesting publication of SIR after Examiner action
FEE CAI	CULATION	115	110	215	55	Extension for reply within first month
BASIC FILING FEE		116	380	216	200	Extension of time within second month
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101 710 201 395	Utility filing fee \$710	119	300	219	155	Notice of Appeal
310 310 206 165	Design filing fee \$	120	300	220	155	Filing a brief in support of an appeal
107 480 207 270	Plant filing fee \$	121	260	221	135	Request for oral hearing
108 760 208 395	Reissue filing fee \$	138	1,510	138	1,510	Petition to institute a pubic use proceeding
1 14 150 214 75	Provisional filing fee \$	140	110	240	55	Petition to revive - unavoidable
#		141	1,210	241	660	Petition to revive - unintentional
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2. EXTRA CLAIM FEES		143 144	430 580	243 244	225 335	Design issue fee Plant issue fee
	Fee	122	130	122	130	Petitions to the Commissioner
	a Claims from Fee Paid	123	50	123	50	Petitions related to provisional applications
Total Claims 14 -20**=	below 0 x 18 = 0	126	240	126	240	Submission of Information Disclosure Stmt
Independent 2 -3** =	0 x 80 = 0	581	40	581	40	Recording each patent assignment per properly (time number of properties)
Claims		146	760	246	395	Filing a submission after final rejection (37 CFR 1 129(a))
Multiple Dependent	260 =	149	760	249	395	For each additional invention to be
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MICROPROCESSOR HAVING A SET OF BYTE INTERMINGLING INSTRUCTIONS

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David Hoyle Vishal Markandey Lewis Nardini

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This application claims priority under 35 USC §119(e)(1) of Provisional Application No. 60/183,527, filed February 18, 2000 (TI-30302PS) and of Provisional Application No. 60/173,761, filed December 30, 1999 (TI-26011P).

NOTICE

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Technical Field of the Invention

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This invention relates to data processing devices, electronic processing and control systems and methods of their manufacture and operation, and particularly relates to microprocessors optimized for digital signal processing.

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Background of the Invention

Generally, a microprocessor is a circuit that combines the instructionhandling, arithmetic, and logical operations of a computer on a single semiconductor integrated circuit. Microprocessors can be grouped into two general classes, namely general-purpose microprocessors and special-purpose microprocessors. General-purpose microprocessors are designed to be programmable by the user to perform any of a wide range of tasks, and are therefore often used as the central processing unit (CPU) in equipment such as personal computers. Special-purpose microprocessors, in contrast, are designed to provide performance improvement for specific predetermined arithmetic and logical functions for which the user intends to use the microprocessor. By knowing the primary function of the microprocessor, the designer can structure the microprocessor architecture in such a manner that the performance of the specific function by the special-purpose microprocessor greatly exceeds the performance of the same function by a general-purpose microprocessor regardless of the program implemented by the user.

One such function that can be performed by a special-purpose microprocessor at a greatly improved rate is digital signal processing. Digital signal processing generally involves the representation, transmission, and manipulation of signals, using numerical techniques and a type of special-purpose microprocessor known as a digital signal processor (DSP). Digital signal processing typically requires the manipulation of large volumes of data, and a digital signal processor is optimized to efficiently perform the intensive computation and memory access operations associated with this data manipulation. For example, computations for performing Fast Fourier Transforms (FFTs) and for implementing digital filters consist to a large degree of repetitive operations such as multiply-and-add and multiple-bit-shift. DSPs can be specifically adapted for these repetitive functions, and

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provide a substantial performance improvement over general-purpose microprocessors in, for example, real-time applications such as image and speech processing.

DSPs are central to the operation of many of today's electronic products, such as high-speed modems, high-density disk drives, digital cellular phones, complex automotive systems, and video-conferencing equipment. DSPs will enable a wide variety of other digital systems in the future, such as video-phones, network processing, natural speech interfaces, and ultra-high speed modems. The demands placed upon DSPs in these and other applications continue to grow as consumers seek increased performance from their digital products, and as the convergence of the communications, computer and consumer industries creates completely new digital products.

Microprocessor designers have increasingly endeavored to exploit parallelism to improve performance. One parallel architecture that has found application in some modern microprocessors utilizes multiple instruction fetch packets and multiple instruction execution packets with multiple functional units.

Digital systems designed on a single integrated circuit are referred to as an application specific integrated circuit (ASIC). MegaModules are being used in the design of ASICs to create complex digital systems a single chip. (MegaModule is a trademark of Texas Instruments Incorporated.) Types of MegaModules include SRAMs, FIFOs, register files, RAMs, ROMs, universal asynchronous receiver-transmitters (UARTs), programmable logic arrays and other such logic circuits. MegaModules are usually defined as integrated circuit modules of at least 500 gates in complexity and having a complex ASIC macro function. These MegaModules are predesigned and stored in an ASIC design library. The MegaModules can then be selected by a designer and placed within a certain area on a new IC chip.

Designers have succeeded in increasing the performance of DSPs, and microprocessors in general, by increasing clock speeds, by removing data processing bottlenecks in circuit architecture, by incorporating multiple execution units on a single processor circuit, and by developing optimizing compilers that schedule operations to be executed by the processor in an efficient manner. The increasing demands of technology and the marketplace make desirable even further structural and process improvements in processing devices, application systems and methods of operation and manufacture.

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Summary of the Invention

An illustrative embodiment of the present invention seeks to provide a microprocessor, and a method for operating a microprocessor that improves digital signal processing performance. Aspects of the invention are specified in the claims.

In an embodiment of the present invention, a digital signal processor is provided with byte intermingling circuitry for selecting fields from a selected pair of source operands and intermingling the selected fields in an order in accordance with each one of a set of byte intermingling instructions.

In an embodiment of the invention, a 32-bit operand is treated as four 8-bit byte fields and the four fields are selected separately. In another embodiment, an operand size different from 32-bits may be operated on, and the field sizes may be different than eight bits.

In an embodiment of the invention, one instruction is provided that performs a shift right and byte merge operation. Another instruction is provided that performs a shift left and byte merge operation. Another instruction is provided that perform a byte swap operation. A set of instructions are provided that perform various byte packing and unpacking operations.

Brief Description of the Drawings

Other features and advantages of the present invention will become apparent by reference to the following detailed description when considered in conjunction with the accompanying drawings, in which:

Figure 1 is a block diagram of a digital signal processor (DSP), showing components thereof pertinent to an embodiment of the present invention;

Figure 2 is a block diagram of the functional units, data paths and register files of Figure 1;

Figures 3A-3J show an opcode map for the DSP of Figure 1;

Figure 4 is a timing diagram illustrating instruction execution pipeline phase of the processor of Figure 1;

Figure 5A and 5B illustrate an instruction syntaxes for multi-field intermingling instructions;

Figure 6A is a flow chart illustrating operation of a Shift Left and Merge Byte (SHLMB) instruction;

Figure 6B illustrates a destination operand for a Shift Right and Merge Byte (SHRMB) instruction;

Figure 6C illustrates a destination operand for a Swap half word (SWAP2) instruction;

Figure 6D illustrates a destination operand for a Swap Bytes is each half word (SWAP4) instruction;

Figure 6E illustrates a destination operand for a Pack two low half words (PACK2) instruction;

Figure 6F illustrates a destination operand for a Pack two High half words (PACKH2) instruction;

Figure 6G illustrates a destination operand for a Pack High bytes of four half words (PACKH4) instruction:

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Figure 6H illustrates a destination operand for a Pack High half word and Low half word (PACKHL2) instruction;

Figure 6I illustrates a destination operand for a Pack Low bytes of Four half words (PACKL4) instruction;

Figure 6J illustrates a destination operand for a Pack Low half word and High half words (PACKLH2) instruction;

Figure 6K illustrates a destination operand for an Unpack High Unsigned 8-bit to unsigned 16-bit (UNPKHU4) instruction;

Figure 6L illustrates a destination operand for an Unpack Low Unsigned 8-bit to unsigned 16-bit (UNPKLU4) instruction;

Figure 7A is a block diagram illustrating a multi-field intermingling circuit for performing a set of byte intermingling instructions within an .L functional unit of the processor of Figure 1;

Figure 7B is a more detailed block diagram of the intermingling circuit of Figure 7A;

Figure 7C is an alternate embodiment of an intermingling circuit;

Figure 8 is a block diagram of an alternative embodiment of the processor of Figure 1; and

Figure 9 illustrates an exemplary implementation of a digital system that includes an embodiment of the present invention in a mobile telecommunications device.

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Detailed Description of Embodiments of the Invention

Figure 1 is a block diagram of a microprocessor 1 which has an embodiment of the present invention. Microprocessor 1 is a VLIW digital signal processor ("DSP"). In the interest of clarity, Figure 1 only shows those portions of microprocessor 1 that are relevant to an understanding of an embodiment of the present invention. Details of general construction for DSPs are well known, and may be found readily elsewhere. For example, U.S. Patent 5,072,418 issued to Frederick Boutaud, et al, describes a DSP in detail and is incorporated herein by reference. U.S. Patent 5,329,471 issued to Gary Swoboda, et al, describes in detail how to test and emulate a DSP and is incorporated herein by reference. Details of portions of microprocessor 1 relevant to an embodiment of the present invention are explained in sufficient detail hereinbelow, so as to enable one of ordinary skill in the microprocessor art to make and use the invention.

In microprocessor 1 there are shown a central processing unit (CPU) 10, data memory 22, program memory 23, peripherals 60 and an external memory interface (EMIF) with a direct memory access (DMA) 61. CPU 10 further has an instruction fetch/decode unit 10a-c, a plurality of execution units, including an arithmetic and load/store unit D1, a multiplier M1, an ALU/shifter unit S1, an arithmetic logic unit ("ALU") L1, a shared multiport register file 20a from which data are read and to which data are written. Instructions are fetched by fetch unit 10a from instruction memory 23 over a set of busses 41. Decoded instructions are provided from the instruction fetch/decode unit 10a-c to the functional units D1, M1, S1, and L1 over various sets of control lines which are not shown. Data are provided to/from the register file 20a from/to to load/store units D1 over a first set of busses 32a, to multiplier M1 over a second set of busses 34a, to ALU/shifter unit S1 over a third set of busses 36a and to ALU L1 over a fourth set of busses 38a.

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Data are provided to/from the memory 22 from/to the load/store units D1 via a fifth set of busses 40a. Note that the entire data path described above is duplicated with register file 20b and execution units D2, M2, S2, and L2. In this embodiment of the present invention, two unrelated aligned double word (64 bits) load/store transfers can be made in parallel between CPU 10 and data memory 22 on each clock cycle using bus set 40a and bus set 40b.

A single non-aligned double word load/store transfer is performed by scheduling a first .D unit resource and two load/store ports on memory 22. Advantageously, an extraction circuit is connected to the memory subsystem to provide a non-aligned data item extracted from two aligned data items requested by the .D unit. Advantageously, a second .D unit can perform 32-bit logical or arithmetic instructions in addition to the .S and .L units while the address port of the second .D unit is being used to transmit one of two contiguous addresses provided by the first .D unit. Furthermore, a non-aligned access near the end of a circular buffer region in the target memory provides a non-aligned data item that wraps around to the other end of the circular buffer.

Emulation circuitry 50 provides access to the internal operation of integrated circuit 1 that can be controlled by an external test/development system (XDS) 51. External test system 51 is representative of a variety of known test systems for debugging and emulating integrated circuits. One such system is described in U.S. Patent 5,535,331 which is incorporated herein by reference. Test circuitry 52 contains control registers and parallel signature analysis circuitry for testing integrated circuit 1.

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Note that the memory 22 and memory 23 are shown in Figure 1 to be a part of a microprocessor 1 integrated circuit, the extent of which is represented by the box 42. The memories 22-23 could just as well be external to the microprocessor 1 integrated circuit 42, or part of it could reside on the integrated circuit 42 and part of it be external to the integrated circuit 42.

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These are matters of design choice. Also, the particular selection and number of execution units are a matter of design choice, and are not critical to the invention.

When microprocessor 1 is incorporated in a data processing system, additional memory or peripherals may be connected to microprocessor 1, as illustrated in Figure 1. For example, Random Access Memory (RAM) 70, a Read Only Memory (ROM) 71 and a Disk 72 are shown connected via an external bus 73. Bus 73 is connected to the External Memory Interface (EMIF) which is part of functional block 61 within microprocessor 1. A Direct Memory Access (DMA) controller is also included within block 61. The DMA controller is generally used to move data between memory and peripherals within microprocessor 1 and memory and peripherals which are external to microprocessor 1.

In the present embodiment, CPU core 10 is encapsulated as a MegaModule, however, other embodiments of the present invention may be in custom designed CPU's or mass market microprocessors, for example.

A detailed description of various architectural features of the microprocessor of Figure 1 is provided in coassigned application S.N. 09/012,813 (TI-25311) and is incorporated herein by reference. A description of enhanced architectural features and an extended instruction set not described herein for CPU 10 is provided in coassigned U.S. Patent application S.N. ______ (TI-30302) Microprocessor with Improved Instruction Set Architecture and is incorporated herein by reference.

Figure 2 is a block diagram of the execution units and register files of the microprocessor of Figure 1 and shows a more detailed view of the buses connecting the various functional blocks. In this figure, all data busses are 32 bits wide, unless otherwise noted. There are two general-purpose register files (A and B) in the processor's data paths. Each of these files contains 32 32-bit registers (A0-A31 for file A and B0-B31 for file B). The general-

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purpose registers can be used for data, data address pointers, or condition registers. Any number of reads of a given register can be performed in a given cycle.

The general-purpose register files support data ranging in size from packed 8-bit data through 64-bit fixed-point data. Values larger than 32 bits, such as 40-bit long and 64-bit double word quantities, are stored in register pairs, with the 32 LSBs of data placed in an even-numbered register and the remaining 8 or 32 MSBs in the next upper register (which is always an odd-numbered register). Packed data types store either four 8-bit values or two 16-bit values in a single 32-bit register.

There are 32 valid register pairs for 40-bit and 64-bit data, as shown in Table 1. In assembly language syntax, a colon between the register names denotes the register pairs and the odd numbered register is encoded in the instruction opcode.

Table 1 - 40-Bit/64-Bit Register Pairs

Regist	er Files
A	В
A1:A0	B1:B0
A3:A2	B3:B2
A5:A4	B5:B4
A7:A6	67:B6
A9:A8	B9:B8
A11:A10	B11:B10
A13:A12	B13:B12
A15:A14	B15:B14
A17:A16	B17:B16
A19:A18	B19:B18
A21:A20	B21:B20
A23:A22	B23:B22
A25:A24	B25:B24
A27:A26	B27:B26
A29:A28	B29:B28
A31:A30	B31:B30

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For 40-bit data, operations requiring a long input ignore the 24 MSBs of the odd register. Operations producing a long result zero-fill the 24 MSBs of the odd register. The even register is encoded in the opcode.

The eight functional units in processor 10's data paths are be divided into two groups of four; each functional unit in one data path is almost identical to the corresponding unit in the other data path. The functional units are described in Table 2.

Besides being able to perform 32-bit data manipulations, processor 10 also contains many 8-bit and 16-bit data instructions in the instruction set. For example, the MPYU4 instruction performs four 8x8 unsigned multiplies with a single instruction on a .M unit. The ADD4 instruction performs four 8-bit additions with a single instruction on a .L unit.

Table 2 Functional Units and Operations Performed

Functional Unit	Fixed-Point Operations
.L unit (.L1, .L2)	32/40-bit arithmetic and compare operations
.n unit (.n1, .n2)	32-bit logical operations
	Leftmost 1 or 0 counting for 32 bits
	Normalization count for 32 and 40 bits
	Byte shifts
	Data packing/unpacking
	5-bit constant generation
	Paired 16-bit arithmetic operations
	Quad 8-bit arithmetic operations
	Paired 16-bit min/max operations
	Quad 8-bit min/max operations
.S unit (.S1, .S2)	32-bit arithmetic operations
	32/40-bit shifts and 32-bit bit-field operations
	32-bit logical operations
	Branches
	Constant generation
	Register transfers to/from control register file (.S2 only)
	Byte shifts
	Data packing/unpacking
	Paired 16-bit compare operations
	Quad 8-bit compare operations
	Paired 16-bit shift operations
	Paired 16-bit saturated arithmetic operations
·	Quad 8-bit saturated arithmetic operations
.M unit (.M1, .M2)	16 x 16 multiply operations
	16 x 32 multiply operations
	Bit expansion
	Bit interleaving/de-interleaving
	Quad 8 x 8 multiply operations
	Paired 16 x 16 multiply operations
	Paired 16 x 16 multiply with add/subtract operations
	Quad 8 x 8 multiply with add operations
	Variable shift operations
	Rotation Galois Field Multiply
	Galois Field Multiply
.D unit (.D1, .D2)	32-bit add, subtract, linear and circular address calculation
	Loads and stores with 5-bit constant offset
	Loads and stores with 15-bit constant offset (.D2 only)
	Load and store double words with 5-bit constant
	Load and store non-aligned words and double words
	5-bit constant generation
	32-bit logical operations

Most data lines in the CPU support 32-bit operands, and some support long (40-bit) and double word (64-bit) operands. Each functional unit has its own 32-bit write port into a general-purpose register file (Refer to Figure 2). All units ending in 1 (for example, .L1) write to register file A 20a and all

units ending in 2 write to register file B 20b. Each functional unit has two 32-bit read ports for source operands src1 and src2. Four units (.L1, .L2, .S1, and .S2) have an extra 8-bit-wide port for 40-bit long writes, as well as an 8-bit input for 40-bit long reads. Because each unit has its own 32-bit write port, when performing 32 bit operations all eight units can be used in parallel every cycle. Since each multiplier can return up to a 64-bit result, two write ports are provided from the multipliers to the register file.

Register File Cross Paths

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Each functional unit reads directly from and writes directly to the register file within its own data path. That is, the .L1, .S1, .D1, and .M1 units write to register file A and the .L2, .S2, .D2, and .M2 units write to register file B. The register files are connected to the opposite-side register file's functional units via the 1X and 2X cross paths. These cross paths allow functional units from one data path to access a 32-bit operand from the opposite side's register file. The 1X cross path allows data path A's functional units to read their source from register file B. Similarly, the 2X cross path allows data path B's functional units to read their source from register file A.

All eight of the functional units have access to the opposite side's register file via a cross path. The .M1, .M2, .S1, .S2, .D1 and .D2 units' src2 inputs are selectable between the cross path and the same side register file. In the case of the .L1 and .L2 both src1 and src2 inputs are also selectable between the cross path and the same-side register file.

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Only two cross paths, 1X and 2X, exist in this embodiment of the architecture. Thus the limit is one source read from each data path's opposite register file per cycle, or a total of two cross-path source reads per cycle. Advantageously, multiple units on a side may read the same cross-path source simultaneously. Thus the cross path operand for one side may be used by any one, multiple or all the functional units on that side in an execute

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packet. In the C62x/C67x, only one functional unit per data path, per execute packet could get an operand from the opposite register file.

A delay clock cycle is introduced whenever an instruction attempts to read a register via a cross path that was updated in the previous cycle. This is known as a cross path stall. This stall is inserted automatically by the hardware; no NOP instruction is needed. It should be noted that no stall is introduced if the register being read is the destination for data loaded by a LDx instruction.

Memory, Load and Store Paths

Processor 10 supports double word loads and stores. There are four 32-bit paths for loading data for memory to the register file. For side A, LD1a is the load path for the 32 LSBs; LD1b is the load path for the 32 MSBs. For side B, LD2a is the load path for the 32 LSBs; LD2b is the load path for the 32 MSBs. There are also four 32-bit paths, for storing register values to memory from each register file. ST1a is the write path for the 32 LSBs on side A; ST1b is the write path for the 32 MSBs for side A. For side B, ST2a is the write path for the 32 LSBs; ST2b is the write path for the 32 MSBs.

Some of the ports for long and double word operands are shared between functional units. This places a constraint on which long or double word operations can be scheduled on a datapath in the same execute packet.

Data Address Paths

Bus 40a has an address bus DA1 which is driven by mux 200a. This allows an address generated by either load/store unit D1 or D2 to provide a memory address for loads or stores for register file 20a. Data Bus LD1 loads data from an address in memory 22 specified by address bus DA1 to a register in load unit D1. Unit D1 may manipulate the data provided prior to storing it in register file 20a. Likewise, data bus ST1 stores data from

register file 20a to memory 22. Load/store unit D1 performs the following operations: 32-bit add, subtract, linear and circular address calculations. Load/store unit D2 operates similarly to unit D1, with the assistance of mux 200b for selecting an address.

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The DA1 and DA2 resources and their associated data paths are specified as T1 and T2 respectively. T1 consists of the DA1 address path and the LD1a, LD1b, ST1a and ST1b data paths. Similarly, T2 consists of the DA2 address path and the LD2a, LD2b, ST2a and ST2b data paths. The T1 and T2 designations appear in functional unit fields for load and store instructions.

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For example, the following load instruction uses the .D1 unit to generate the address but is using the LD2a path resource from DA2 to place the data in the B register file. The use of the DA2 resource is indicated with the T2 designation, for example: LDW .D1T2 *A0[3], B1.

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Table 3 defines the mapping between instructions and functional units for a set of basic instructions included in a DSP described in U.S. Patent S.N. 09/012,813 (TI-25311, incorporated herein by reference). Table 4 defines a mapping between instructions and functional units for a set of extended instructions in an embodiment of the present invention. Alternative embodiments of the present invention may have different sets of instructions and functional unit mapping. Table 3 and Table 4 are illustrative and are not exhaustive or intended to limit various embodiments of the present invention.

Table 3 Instruction to Functional Unit Mapping of Basic Instructions

.L Unit	.M Unit	.S Unit	.D Unit
ABS	MPY	ADD	ADD
ADD	SMPY	ADDK	ADDA
AND		ADD2	LD mem
CMPEQ		AND	LD mem (15-bit offset) (D2 only)
CMPGT		B disp	MV
CMPGTU		B IRP	NEG
CMPLT		B NRP	ST mem
CMPLTU		B reg	ST mem (15-bit offset) (D2 only)
LMBD		CLR	SUB
MV		EXT	SUBA
NEG		EXTU	ZERO
NORM		MVC	
NOT		MV	
OR		MVK	
SADD		MVKH	
SAT		NEG	
SSUB		NOT	
SUB		OR	
SUBC		SET	
XOR		SHL	
ZERO		SHR	
		SHRU	
		SSHL	
		STP (S2 only)	
		SUB	
		SUB2	
		XOR	
		ZERO	

Table 4 Instruction to Functional Unit Mapping of Extended Instructions

.L unit	.M unit	.S unit	.D unit
ABS2	AVG2	ADD2	ADD2
ADD2	AVGU4	ADDKPC	AND
ADD4	BITC4	AND	ANDN
AND	BITR	ANDN	LDDW
ANDN	DEAL	BDEC	LDNDW
MAX2	DOTP2	BNOP	LDNW
MAXU4	DOTPN2	BPOS	MVK
MIN2	DOTPNRSU2	CMPEQ2	OR
MINU4	DOTPNRUS2	CMPEQ4	STDW
	DOTPRSU2	CMPGT2	
	DOTPRUS2	CMPGTU4	
MVK	DOTPSU4	CMPLT2	STNDW
	DOTPUS4		
OR	DOTPU4	CMPLTU4	STNW
PACK2	GMPY4	MVK	SUB2
PACKH2	MPY2	OR	XOR
PACKH4	MPYHI	PACK2	
PACKHL2	MPYHIR	PACKH2	
	MPYIH		
	MPYIHR		
PACKL4	MPYIL	PACKHL2	
	MPYILR		
	MPYLI		
PACKLH2	MPYLIR	PACKLH2	
SHLMB	MPYSU4	SADD2	
	MPYUS4		
SHRMB	MPYU4	SADDU4	
SUB2	MVD	SADDSU2	
		SADDUS2	
SUB4	ROTL	SHLMB	
SUBABS4	SHFL	SHR2	
SWAP2	SMPY2	SHRMB	
SWAP4	SSHVL	SHRU2	
UNPKHU4	SSHVR	SPACK2	
UNPKLU4	XPND2	SPACKU4	
XOR	XPND4	SUB2	
		SWAP2	
		UNPKHU4	
		UNPKLU4	
		XOR	

The DSP's opcode map is shown in Figures 3A-3J. Refer to the instruction descriptions later herein for explanations of the field syntax and values. An instruction syntax is used to describe each instruction. The opcode map breaks down the various bit fields that make up each instruction. There are certain instructions that can be executed on more than one functional unit, as was shown in Table 4. The syntax specifies the functional unit and various resources used by an instruction, typically as follows:

EXAMPLE (.unit) src, dst

The following are examples of what the syntax looks like for the ADD instruction:

- 1) ADD (unit) src1, src2, dst
- 2) ADDU (.unit) src1, src2, dst
- 3) ADD (unit) src2, src1, dstunit = .L1, .L2, .S1, .S2, .D1, .D2

src and dst indicate source and destination respectively. The (.unit) dictates which functional unit the instruction is mapped to (.L1, .L2, .S1, .S2, .M1, .M2, .D1, or .D2). This instruction has three opcode map fields: src1, src2, and dst.

The addressing modes for instructions that access memory are linear, circular using BK0, and circular using BK1. The mode is specified by an addressing mode register (AMR) contained in control register file 102. Eight registers can perform circular addressing. A4-A7 are used by the .D1 unit and B4-B7 are used by the .D2 unit. No other units can perform circular addressing modes. For each of these registers, the AMR specifies the addressing mode.

All instructions can be conditional. The condition is controlled by a 3bit (creg) field specifying a register to be tested, and a 1-bit field (z) specifying a test for zero or nonzero, as shown in Figures 3A-3J. The four MSBs of every opcode are creg and z. The specified register is tested at the beginning of the E1 instruction execution pipeline stage for all instructions. The pipeline is described later herein. If z = 1, the test is for equality with zero. If z = 0, the test is for nonzero. The case of condition register field (creg) = 0 and z = 0 is treated as always true to allow instructions to be executed unconditionally. The creg register field is encoded as shown in Table 5. Conditional instructions are represented by "[]" surrounding the condition register.

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Table 5 Registers That Can Be Tested by Conditional Operations

	Creg		z	Register Tested
31	30	29	28	
0	0	0	0	Unconditional.
0	0	0	1	Reserved: When selected this indicates a SWBP instruction
0	0	1	z	В0
0	1	0	z	B1
0	1	1	z	B2
1	0	0	z	
1	0	0	z	A1
1	0	1	z	A2
1	1	x	х	Reserved

Note: x is don't care for reserved cases.

Instructions are always fetched eight at a time. This constitutes a *fetch* packet. The execution grouping of the fetch packet is specified by the p-bit, bit zero, of each instruction. Fetch packets are 8-word aligned.

The p bit controls the parallel execution of instructions. The p bits are scanned from left to right (lower to higher address). If the p bit of instruction i is 1, then instruction i + 1 is to be executed in parallel with (in the same cycle as) instruction i. If the p-bit of instruction i is 0, then instruction i + 1 is executed in the cycle after instruction i. All instructions executing in parallel constitute an execute packet. An execute packet can contain up to eight instructions. All instructions in an execute packet must use a unique functional unit.

Pipeline Operation

The DSP pipeline has several key features which improve performance, decrease cost, and simplify programming. They are: increased pipelining eliminates traditional architectural bottlenecks in program fetch, data access, and multiply operations; control of the pipeline is simplified by eliminating pipeline interlocks; the pipeline can dispatch eight parallel instructions every cycle; parallel instructions proceed simultaneously through the same pipeline phases; sequential instructions proceed with the same relative pipeline phase

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difference; and load and store addresses appear on the CPU boundary during the same pipeline phase, eliminating read-after-write memory conflicts.

A multi-stage memory pipeline is present for both data accesses and program fetches. This allows use of high-speed synchronous memories both on-chip and off-chip, and allows infinitely nestable zero-overhead looping with branches in parallel with other instructions.

There are no internal interlocks in the execution cycles of the pipeline, so a new execute packet enters execution every CPU cycle. Therefore, the number of CPU cycles for a particular algorithm with particular input data is fixed. If during program execution, there are no memory stalls, the number of CPU cycles equals the number of clock cycles for a program to execute.

Performance can be inhibited by stalls from the memory system, stalls for cross path dependencies, or interrupts. The reasons for memory stalls are determined by the memory architecture. Cross path stalls are described in detail in U.S. Patent S.N. _____ (TI-30563), to Steiss, et al and is incorporated herein by reference. To fully understand how to optimize a program for speed, the sequence of program fetch, data store, and data load requests the program makes, and how they might stall the CPU should be understood.

The pipeline operation, from a functional point of view, is based on CPU cycles. A CPU cycle is the period during which a particular execute packet is in a particular pipeline stage. CPU cycle boundaries always occur at clock cycle boundaries; however, stalls can cause CPU cycles to extend over multiple clock cycles. To understand the machine state at CPU cycle boundaries, one must be concerned only with the execution phases (E1-E5) of the pipeline. The phases of the pipeline are shown in Figure 4 and described in Table 6.

Table 6 Pipeline Phase Description

Pipeline	Pipeline Phase	Symbol	During This Phase	Instruction Types Completed
Program Fetch	Program Address Generate	PG	Address of the fetch packet is determined.	-
	Program Address Send	PS	Address of fetch packet is sent to memory.	
	Program Wait	PW	Program memory access is performed.	
	Program Data Receive	PR	Fetch packet is expected at CPU boundary.	
Program Decode	Dispatch	DP	Next execute packet in fetch packet determined and sent to the appropriate functional units to be decoded.	
	Decode	DC	Instructions are decoded at functional units.	
Execute	Execute 1	E1	For all instruction types, conditions for instructions are evaluated and operands read. Load and store instructions: address generation is computed and address modifications written to register file [†] Branch instructions: affects branch fetch packet in PG phase [†] Single-cycle instructions: results are written to a register file [†]	cycle
	Execute 2	E2	Load instructions: address is sent to memory † Store instructions and STP: address and data are sent to memory † Single-cycle instructions that saturate results set the SAT bit in the Control Status Register (CSR) if saturation occurs. † Multiply instructions: results are written to a register file †	Stores STP Multiplies
	Execute 3	E3	Data memory accesses are performed. Any multiply instruction that saturates results sets the SAT bit in	
	To the state of th	P.	the Control Status Register (CSR) if saturation occurs.	
	Execute 4	E4	Load instructions: data is brought to CPU boundary	
	Execute 5	E5	Load instructions: data is loaded into register †	Loads

[†]This assumes that the conditions for the instructions are evaluated as true. If the condition is evaluated as false, the instruction will not write any results or have any pipeline operation after E1.

Referring again to Figure 4 and Figure 1, the instruction execution pipeline of processor 10 involves a number of discrete stages, generally demarcated by temporary latches or registers to pass the results of one stage to the next. Instruction pipeline phases PG, PS, PW, and PR all involve instruction fetching and are embodied in program fetch circuit 10 in association with program memory subsystem 23. Pipeline phases DP and DC involve instruction decoding; phase DP is embodied in dispatch circuitry 10b,

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while pipeline phase DC is embodied in decode circuitry 10c. The execution phases E1-E5 are embodied in stages embodied within each functional unit L, S, M and D. For example, the D units embody all five execute stage in association with memory subsystem 22. Other of the functional units do not embody all five execution phase, but only what is required for the instruction types that are executed by a particular functional unit.

The execution of instructions can be defined in terms of delay slots, as shown in Table 7. A delay slot is a CPU cycle that occurs after the first execution phase (E1) of an instruction in which results from the instruction are not available. For example, a multiply instruction has 1 delay slot, this means that there is 1 CPU cycle before another instruction can use the results from the multiply instruction.

Table 7 Delay Slot Summary

Instruction Type	Delay Slots	Execute Stages Used
Branch (The cycle when the target enters E1)	5	E1-branch target E1
Load (LD) (Incoming Data)	4	E1 - E5
Load (LD) (Address Modification)	0	E1
Multiply	1	E1 - E2
Single-cycle	0	E1
Store	0	E1
NOP (no execution pipeline operation)	-	-
STP (no CPU internal results written)	-	-

Single cycle instructions execute during the E1 phase of the pipeline. The operand is read, operation is performed and the results are written to a register all during E1. These instructions have no delay slots.

Multiply instructions complete their operations during the E2 phase of the pipeline. In the E1 phase, the operand is read and the multiply begins. In the E2 phase, the multiply finishes, and the result is written to the destination (dst) register. Multiply instructions have 1 delay slot.

Load instructions have two results: data loaded from memory and address pointer modification.

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Data loads complete their operations during the E5 phase of the pipeline. In the E1 phase, the address of the data is computed. In the E2 phase, the data address is sent to data memory. In the E3 phase, a memory read is performed. In the E4 stage, the data is received at the CPU core boundary. Finally, in the E5 phase, the data is loaded into a register. Because data is not written to the register until E5, these instructions have 4 delay slots. Because pointer results are written to the register in E1, there are no delay slots associated with the address modification.

Store instructions complete their operations during the E3 phase of the pipeline. In the E1 phase, the address of the data is computed. In the E2 phase, the data address is sent to data memory. In the E3 phase, a memory write is performed. The address modification is performed in the E1 stage of the pipeline. Even though stores finish their execution in the E3 phase of the pipeline, they have no delay slots and follow the following rules (i = cycle):

- 1) When a load is executed before a store, the old value is loaded and the new value is stored.
- 2) When a store is executed before a load, the new value is stored and the new value is loaded.
- 3) When the instructions are in are in parallel, the old value is loaded and the new value is stored.

Byte Intermingling Instructions

The DSP of Figure 1, which is an embodiment of the present invention, includes an extensive set of packed data instructions that provide features of single instruction, multiple data (SIMD) operation. These instructions operate directly on packed data to streamline data flow and increase instruction set efficiency. By so doing, performance of the processor is improved. They are summarized in Table 8 below:

Table 8 - Instructions for Operating Directly on Packed Data

Operation	Quad 8-bit	Paired 16-bit
Multiply	X	X
Multiply with Saturation		X
Addition/Subtraction	X	X *
Addition with Saturation	X	X
Absolute Value		X
Subtract with Absolute Value	X	
Compare	X	X
Shift		X
Data Pack/Unpack	X	X
Data Pack with Saturation	X	X
Dot product with optional negate	X	X
Min/Max/Average	X	X
Bit-expansion (Mask generation)	X	X

In order to simplify manipulation of the packed data, a set of byte intermingling instructions is provided. This set of instructions is described in Table 9.

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Table 9 - Byte Intermingling Instruction Set Description

PACK2 Pack 16lsb, 16lsb into Packed 16-bit: The PACK2 instruction takes the lower h src1 and src2 and packs them both into dst. The lower half-word of src1 is place half-word of dst. The lower half-word of dst This instruction is useful for manipulating and preparing pairs of 16-bit values the packed arithmetic operations, such as ADD2.	d in the upper
This instruction is useful for manipulating and preparing pairs of 16-bit values	
	to be used by
PACKH2 Pack 16msb, 16msb into Packed 16-bit: The PACKH2 instruction takes the up	per half-words
from src1 and src2 and packs them both into dst. The upper half-word of src1 is	
upper half-word of dst. The upper half-word of src2 is placed in the lower half-word	d of dst .
This instruction is useful for manipulating and preparing pairs of 16-bit values to	be used by the
packed arithmetic operations, such as ADD2.	
PACKH4 Pack High Bytes of Four Half-words into Packed 8-bit: The PACKH4 instruction in	
bytes of the two half-words in src1 and src2 and packs them into dst. The bytes fr	
packed into the most significant bytes of dst , and the bytes from $src2$ will be packe significant bytes of dst .	u mto the least
Specifically, the high byte of the upper half-word of <i>src1</i> is moved to the upper by	te of the upper
half-word of dst. The high byte of the lower half-word of src1 is moved to the low	
upper half-word of dst. The high byte of the upper half-word of src2 is moved to th	
the lower half-word of dst. The high byte of the lower half-word of src2 is moved to	the lower byte
of the lower half-word of dst.	
PACKHL2 Pack 16msb, 16lsb into Packed 16-bit: The PACKHL2 instruction takes the upper	
src1 and the lower half-word from $src2$ and packs them both into dst . The upper half-word from $src2$ and packs them both into dst .	
is placed in the upper half-word of dst. The lower half-word of src2 is placed in	the lower half-
word of dst.	. 4
This instruction is useful for manipulating and preparing pairs of 16-bit values the packed arithmetic operations, such as ADD2.	to be used by
PACKL4 Pack Low Bytes of Four Half-words into Packed 8-bit: The PACKL4 instruction	moves the low
bytes of the two half-words in $src2$ and $packs$ them into dst . The bytes fr	
packed into the most significant bytes of dst, and the bytes from src2 will be packe	
significant bytes of dst .	
Specifically, the low byte of the upper half-word of src1 is moved to the upper by	
half-word of dst. The low byte of the lower half-word of src1 is moved to the low	
upper half-word of dst. The low byte of the upper half-word of src2 is moved to the	
the lower half-word of dst . The low byte of the lower half-word of $src2$ is moved to of the lower half-word of dst .	the lower byte
PACKLH2 Pack 16lsb, 16msb into Packed 16-bit: The PACKLH2 instruction takes the lower	half-word from
src1 and the upper half-word from $src2$ and packs them both into dst . The lower half-word	
is placed in the upper half-word of dst. The upper half-word of src2 is placed in	the lower half-
word of dst.	
This instruction is useful for manipulating and preparing pairs of 16-bit values	to be used by
the packed arithmetic operations, such as ADD2. SHLMB Shift Left and Merge Byte: The SHLMB instruction shifts the contents of src2 left.	A her and herto
and then the most significant byte of src1 is merged into the least significant byte	
result is then placed in dst .	e position. The
SHRMB Shift Right and Merge Byte: The SHRMB instruction shifts the contents of src	2 right by one
byte, and then the least significant byte of src1 is merged into the most significan	
The result is then placed in dst.	
SWAP2 Swap Half-words in Each Word (Pseudo-Operation): The SWAP2 is a pseudo-	operation that
takes the lower half-word from src2 and places it in the upper half-word of dst u	
half word from src2 is placed in the lower half-word of dst. It assembles as PAC	KLH2 src, src,
dst.	. 40 ha 3 1
This instruction is useful for manipulating and preparing pairs of 16-bit values	s to be used by
the packed arithmetic operations, such as ADD2. The SWAP2 instruction can be used in conjunction with the SWAP4 instruction	to change the
byte ordering (and therefore, the endianness) of 32-bit data.	. w change life
SWAP4 Swap Bytes in Each Half-word: The SWAP4 instruction exchanges pairs of byt	es within each
half-word of $src2$, placing the result in dst . The values in $src2$ are treated as packet	
Specifically, the upper byte in the upper half-word is placed in the lower byte	o m uno appor

	half-word. Also the upper byte in the lower half-word is placed in the lower byte of the lower half-word while the lower byte in the lower half-word is placed in the upper byte of the lower half word. By itself, this instruction changes the ordering of bytes within half words. This effectively changes the endianness of 16-bit data packed in 32-bit words. The endianness of full 32-bit
	quantities can be changed by using the SWAP4 instruction in conjunction with the SWAP2 instruction
UNPKHU4	Unpack High Unsigned Packed 8-bit to Unsigned Packed 16-bit: The UNPKHU4 instruction moves the two most significant bytes of $src2$ into the two low bytes of the two half-words of dst . Specifically, the upper byte in the upper half-word is placed in the lower byte in the upper half-word while the lower byte of the upper half-word is placed in the lower byte of the lower half-word. The $src2$ bytes are zero-extended when unpacked, filling the two high bytes of the two half-words of dst with zeros.
UNPKLU4	Unpack Low Unsigned Packed 8-bit to Unsigned Packed 16-bit: The UNPKLU4 instruction moves the two least significant bytes of $src2$ into the two low bytes of the two half-words of dst . Specifically, the upper byte in the lower half-word is placed in the lower byte in the upper half-word while the lower byte of the lower half-word is kept in the lower byte of the lower half-word. The $src2$ bytes are zero-extended when unpacked, filling the two high bytes of the two half-words of dst with zeros.

Figure 5A illustrates an instruction syntax for a byte intermingling instructions that selects byte fields from both a first source operand and from a second source operand, such as the Shift Left, Merge Byte (SHLMB) instruction. Figure 5B illustrates an instruction syntax for a byte intermingling instructions that selects byte fields from only one source operand, as the SWAP4 instruction. In this embodiment, all of the byte intermingling instructions can be executed in either .L functional unit 18a or 18b as indicated by unit select bit field 500. The instruction includes a first source operand field (src1) 501 and a second source operand field (src2) 502 that each select a register from associated register file 20a or 20b to access a source operand which is a 32-bit data value. The byte intermingling instructions each perform a byte intermingling operation on various fields selected from the source operands. The values in the source operands are treated as packed data, and the result is written in a corresponding packed format in a destination register specified by a destination field (dst) 504. Each of the byte intermingling instructions in this embodiment, except SWAP4, PACKH4 and PACKL4, can also be executed on either .S unit in response to a different value in type field 510 and opcode field 512.

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Referring still to Figure 5, field 510 defines a class of instruction formats, while opcode field 512 specifies that a particular instruction of this class is one of the byte intermingling instruction listed in Table 25. Crossover control field 514 specifies which register file 20a or 20b will be accessed for a source operand, as discussed previously. Parallel bit 516 indicates if this instruction is to be executed in parallel with an adjacent instruction in a fetch packet, as discussed previously.

As with all of the instructions executed by the DSP of Figure 1, the byte intermingling instructions are conditional based on a predicate register selected by condition register field (creg) 506 and zero indicator bit 508, as discussed previously. Table 10 defines the operation of the SHLMB instruction using pseudo code. Just as with other conditionally executed instructions, if the predicate condition tests false, SHLMB does not complete execution and the write of the *dst* register is inhibited. The other byte intermingling instructions listed in Table 9 have a similar pseudo code, except that different bytes are selected from the first source operand (src1) and the second source operand (src2) and the selected bytes are placed in different orders in the destination operand (dst).

Table 10 - Execution of SHLMB Instruction

```
if (cond) {
   ubyte2(src2) \rightarrow ubyte3(dst);
   ubyte1(src2) \rightarrow ubyte2(dst);
   ubyte0(src2) \rightarrow ubyte1(dst);
   ubyte3(src1) \rightarrow ubyte0(dst);
   }
else nop
```

Figure 6A is a flow chart illustrating operation of a Shift Left and Merge Byte (SHLMB) instruction. The SHLMB instruction shifts the contents of src2 left by one byte, and then the most significant byte of src1 is merged into the least significant byte position. The result is then placed in

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dst. A data value in a first selected source operand 600 is treated as packed, unsigned 8-bit data, located in four distinct fields 600(0-3). A data value in a second selected source operand 602 is also treated as packed unsigned 8-bit data, located in four distinct fields 602(0-3). Three fields 602(2-0) are selected from a least significant portion of the second source operand 602 and shifted left and placed in order in fields 610(3-1) of destination operand 610. A most significant field 600(3) is selected from the first source operand 600 and placed in a least significant position in destination operand 610. Thus, a destination operand is formed that has unsigned bytes selected from the first operand (ua_n) and from the second operand (ub_n) in the following order: ub_2, ub_1, ub_0, and ua_3. In this embodiment, the destination is written during pipeline phase E1 and the SHLMB instruction is categorized has having no delay slots.

Each of the other byte intermingling instructions described in Table 9 operates in a similar manner to select fields from a selected pair of source operands and intermingle the selected fields in an order in accordance with each one of the set of byte intermingling instructions.

Figure 6B illustrates a destination operand for a Shift Right and Merge Byte (SHRMB) instruction. Thus, a destination operand is formed that has unsigned bytes selected from the two source operands in the following order: ua_0, ub_3, ub_2, and ub_1.

Figure 6C illustrates a destination operand for a Swap half word (SWAP2) instruction. Thus, a destination operand is formed that has unsigned bytes selected from just the second source operand in the following order: ub_1, ub_0, ub_3, and ub_2.

Figure 6D illustrates a destination operand for a Swap Bytes in each half word (SWAP4) instruction. Thus, a destination operand is formed that has unsigned bytes selected from just the second source operand in the following order: ub_2, ub_3, ub_0, and ub_1.

Figure 6E illustrates a destination operand for a Pack two low half words (PACK2) instruction. Thus, a destination operand is formed that has unsigned bytes selected from the two source operands in the following order: ua_1, ua_0, ub_1, and ub_0.

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Figure 6F illustrates a destination operand for a Pack two High half words (PACKH2) instruction. Thus, a destination operand is formed that has unsigned bytes selected from the two source operands in the following order: ua_3, ua_2, ub_3, and ub_2.

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Figure 6G illustrates a destination operand for a Pack High bytes of four half words (PACKH4) instruction. Thus, a destination operand is formed that has unsigned bytes selected from the two source operands in the following order: ua_3, ua_1, ub_3, and ub_1.

Figure 6H illustrates a destination operand for a Pack High half word and Low half word (PACKHL2) instruction. Thus, a destination operand is formed that has unsigned bytes selected from the two source operands in the following order: ua_3, ua_2, ub_1, and ub_0.

Figure 6I illustrates a destination operand for a Pack Low bytes of (PACKL4) instruction. Thus, a destination operand is Four half words formed that has unsigned bytes selected from the two source operands in the following order: ua_2, ua_0, ub_2, and ub_0.

Figure 6J illustrates a destination operand for a Pack Low half word and High half words (PACKLH2) instruction. Thus, a destination operand is formed that has unsigned bytes selected from the two source operands in the following order: ua_1 ua_0, ub_3, and ub_2.

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Figure 6K illustrates a destination operand for an Unpack High Unsigned 8-bit to unsigned 16-bit (UNPKHU4) instruction. Thus, a destination operand is formed that has unsigned bytes selected from just the second source operand in the following order: 00000000h, ub_3, 00000000h, and ub_2.

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Figure 6L illustrates a destination operand for an Unpack Low Unsigned 8-bit to unsigned 16-bit (UNPKLU4) instruction. Thus, a destination operand is formed that has unsigned bytes selected from just the second source operand in the following order: 00000000h, ub_1, 00000000h, and ub_0.

Table 11 summarizes the byte ordering of the various destination operands formed by the set of byte intermingling instructions of this embodiment of the present invention.

Table 11 – Summary of Destination Ordering for the Set of Byte Intermingling Instructions

SHLMB	ub_2	ub_1	ub_0	ua_3
SHRMB	ua_0	ub_3	ub_2	ub_1
SWAP2	ub_1	ub_0	ub_3	ub_2.
SWAP4	ub_2	ub_3	ub_0	ub_1
PACK2	ua_1	ua_0	ub_1	ub_0
PACKH2	ua_3	ua_2	ub_3	ub_2
PACKH4	ua_3	ua_1	ub_3	ub_1
PACKHL2	ua_3	ua_2	ub_1	ub_0
PACKL4	ua_2	ua_0	ub_2	ub_0
PACKLH2	ua_1	ua_0	ub_3	ub_2
UNPKHU4	00000000h	ub_3	00000000h	ub_2.
UNPKLU4	00000000h	ub_1	00000000h	ub_0

Figure 7A is a top level block diagram of .L unit 18a or 18b, which is optimized to handle logical operations, although hardware is available for a set of add and subtract operations and also for the multi-field intermingling instruction of the present invention. Logic block 700 performs various Boolean logic functions. Pass gates 700a together with keeper gates 700b form a latch to hold the contents of a first source operand src1, which is selected from either register file 20a or 20b via mux 211 (see Figure 2). Similarly, pass gates 700ca together with keeper gates 700d form a latch to hold the contents of a second source operand src2, which is selected from either register file 20a or 20b via mux 212 (see Figure 2).

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Multiplexer block 702 provides byte intermingling and will be described in more detail with reference to Figure 7B. Pass gates and keeper gates hold first and second source operands src1 and src2.

Left Most Bit Detection (LMBD) block 704 performs leftmost bit detection in src2 or long_src and src2 as specified by src1. First Adder block 706 performs 40-bit arithmetic using long_src and src2 and sign extended src1. Second Adder block 708 performs multi-field arithmetic on packed data fields in src1 and src2.

Long mux 710 selects from either the long_src LNG or the eight msbs ADD1(39:32) output from 40-bit adder 706 to odd-destination mux 720. Other mux 712 selects from the outputs of logic block 700, mux block 702, LMBD block 704, first adder block 706, second adder block 708 and src1. Other mux 712 is divided into four 8-bit sub-blocks that can each be controlled to select respective portions of the six sets of inputs.

Odd destination mux 720 selects from the outputs of a scan register SCAN31:0 (not shown), the first adder 706 bits ADD1(31:0), long mux 710, other mux 712 and zeros or ones. Odd mux 720 is divided into three separately controlled sections for bits 31:16, 15:8 and 7:0. Even destination register 722 selects from the outputs of a scan register SCAN31:0 (not shown), the first adder 706 bits ADD1(31:0), other mux 712 and zeros or ones. Even mux 722 is divided into two separately controlled sections for bits 31:16 and 15:0.

Figure 7B is a more detailed block diagram of intermingling circuit 702 of Figure 7A. Four separately controlled 8-bit multiplexers 730(3:0) are each connected to receive all thirty two bits of source operands src1 and src2, along with logical zeros and logical ones. Thus, any combination of byte fields can be selected from the two source operands and intermingled in any order to form a destination operand on output signal lines mux(31:0). Mux control circuitry 732 receives signals from instruction decoding circuitry 10c (see

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Figure 1) that indicate which byte intermingling instruction is being executed. Separate sets of control signals 732(3:0) are sent to each multiplexer to select to appropriate byte fields from src1 and src2 in response to the byte intermingling instruction that is being executed in order to form a destination operand.

Figure 7C is an alternate embodiment of an intermingling circuit. Four separately controlled 8-bit multiplexers 740(3:0) are each connected to receive only the byte fields of source operands src1 and src2, along with logical zeros, needed to form the intermingled destination operands as indicated in Table 11. Thus, sets of byte fields can be selected from the two source operands and intermingled to form a destination operand on output signal lines mux(31:0) according to the set of byte intermingling instructions described in Table 9. Mux control circuitry 742 receives signals from instruction decoding circuitry 10c (see Figure 1) that indicate which byte intermingling instruction is being executed. Separate sets of control signals 742(3:0) are sent to each multiplexer to select to appropriate byte fields from src1 and src2 in response to the byte intermingling instruction that is being executed in order to form a destination operand.

Thus, the intermingling circuit forms a intermingled destination operand corresponding to a selected number of fields from a selected pair of source operands that are then written into respective field positions of a selected destination register during instruction pipeline E1 in response to a single byte intermingling instruction.

One skilled in the art will recognize that intermingling circuitry 702 may be implemented in a number of different ways, by using various configurations of multiplexers, shifters, barrel shifters, and such. In another embodiment, the intermingling circuitry may be implemented such that a multi-field byte intermingling instruction executes with a different number of delay slots, such as one or two, for example. In another embodiment, a bit

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field having a different width may be intermingled, such as four for example. There may be other varieties of intermingling instructions wherein different opcodes or a parameter is used to identify various bit field widths. In this embodiment of the present invention, intermingling circuitry is included in the L and S units of the CPU. However, in another embodiment, intermingling circuitry may be included in other or different functional units.

In another embodiment of the invention, an intermingled destination operand may be written directly to memory rather to a register file. This is described in more detail in Co-assigned U.S. Patent application S.N.______(TI-26011) entitled *Data Processing System with Register Store/Load Utilizing Data Packing/Unpacking* and is incorporated herein by reference.

Figure 8 is a block diagram of an alternative embodiment of the present invention in a digital system 1000 with processor core 10 of Figure 1. A direct mapped program cache 1010, having 16 kbytes capacity, is controlled by L1 Program (L1P) controller 1011 and connected thereby to the instruction fetch stage 10a. A 2-way set associative data cache, having a 16 Kbyte capacity, is controlled by L1 Data (L1D) controller 1721 and connected thereby to data units D1 and D2. An L2 memory 1030 having four banks of memory, 128 Kbytes total, is connected to L1P 1011 and to L1D 1021 to provide storage for data and programs. External memory interface (EMIF) 1050 provides a 64 bit data path to external memory, not shown, which provides memory data to L2 memory 1030 via extended direct memory access (DMA) controller 1040.

EMIF 1052 provides a 16-bit interface for access to external peripherals, not shown. Expansion bus 1070 provides host and I/O support similarly to host port 60/80 of Figure 1.

Three multi-channel buffered serial ports (McBSP) 1060, 1062, 1064 are connected to DMA controller 1040. A detailed description of a McBSP is

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provided in U.S. Patent S.N. 09/055,011 (TI-26204, Seshan, et al) and is incorporated herein reference.

Figure 9 illustrates an exemplary implementation of a digital system that includes DSP 1 packaged in an integrated circuit 40 in a mobile telecommunications device, such as a wireless telephone 15. Wireless telephone 15 has integrated keyboard 12 and display 14. As shown in Figure 9, DSP 1 is connected to the keyboard 12, where appropriate via a keyboard adapter (not shown), to the display 14, where appropriate via a display adapter (not shown) and to radio frequency (RF) circuitry 16. The RF circuitry 16 is connected to an aerial 18. Advantageously, by providing a set of multi-field byte intermingling instructions complex signal processing algorithms can be written in a more efficient manner to satisfy the demand for enhanced wireless telephony functionality.

Fabrication of digital system 10 involves multiple steps of implanting various amounts of impurities into a semiconductor substrate and diffusing the impurities to selected depths within the substrate to form transistor devices. Masks are formed to control the placement of the impurities. Multiple layers of conductive material and insulative material are deposited and etched to interconnect the various devices. These steps are performed in a clean room environment.

A significant portion of the cost of producing the data processing device involves testing. While in wafer form, individual devices are biased to an operational state and probe tested for basic operational functionality. The wafer is then separated into individual dice which may be sold as bare die or packaged. After packaging, finished parts are biased into an operational state and tested for operational functionality.

Thus, a digital system is provided with a processor having an improved instruction set architecture. The processor is code-compatible with C62xx DSP processors from Texas Instruments Incorporated. It provides a superset

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of the C62x architecture while providing complete code compatibility for existing C62x code. The processor provides extensions to the existing C62x architecture in several areas: register file enhancements, data path extensions, additional functional unit hardware, increased orthogonality of the instruction set, data flow enhancements, 8-bit and 16-bit extensions, and additional instructions that reduce code size and increase register flexibility.

Advantageously, a set of multi-field byte intermingling instructions is provided that provides features of single instruction, multiple data (SIMD) operation. Code size is thereby reduced and performance improved.

As used herein, the terms "applied," "connected," and "connection" mean electrically connected, including where additional elements may be in the electrical connection path. "Associated" means a controlling relationship, such as a memory resource that is controlled by an associated port. The terms assert, assertion, de-assert, de-assertion, negate and negation are used to avoid confusion when dealing with a mixture of active high and active low signals. Assert and assertion are used to indicate that a signal is rendered active, or logically true. De-assert, de-assertion, negate, and negation are used to indicate that a signal is rendered inactive, or logically false.

While the invention has been described with reference to illustrative embodiments, this description is not intended to be construed in a limiting sense. Various other embodiments of the invention will be apparent to persons skilled in the art upon reference to this description. In another embodiment, the source operands may be provided in response to a memory fetch instead of being read from the register file. An intermingling instruction may be executed in another functional unit instead of or in addition to the .L or .S functional units. In another embodiment, a different number of fields, such as eight, for example, could be intermingled. Different opcodes could define the number of fields, for example.

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In another embodiment, fewer byte intermingling instructions may be provided. Conversely, additional selections of byte intermingling may be provided.

In another embodiment, a control register is provided that is loaded with a control word to control the operation of a set of multiplexors and thereby provide a set of multi-field byte intermingling operations that provides features of single instruction, multiple data (SIMD) operation. For example, four bits are allocated in the control register for each byte of the destination. Using the four bits, any byte from any position of the source operands with up to sixteen options can be selected. Therefore, an eight byte destination can be completely specified using a 32-bit control register such that each byte of the destination can receive any byte from eight byte of a source operand, and additionally specify sign-extension, fill with zeros, fill with ones, and leave an original destination byte unaltered to form a merge, for example.

In another embodiment, the various fields overlap each other, such that the result for each field includes bits included within another field.

In another embodiment, values in each field could be treated as something other than an unsigned value, such as a signed value, or a floating point value, for example.

It is therefore contemplated that the appended claims will cover any such modifications of the embodiments as fall within the true scope and spirit of the invention.

What is Claimed is:

1. A digital system comprising a microprocessor having an instruction execution pipeline with a plurality of pipeline phases, wherein the microprocessor comprises:

program fetch circuitry operable to perform a first portion of the plurality of pipeline phases;

instruction decode circuitry connected to receive fetched instructions from the program fetch circuitry, the instruction decode circuitry operable to perform a second portion of the plurality of pipeline phases; and

at least a first functional unit connected to receive control signals from the instruction decode circuitry, the functional unit operable to perform a third portion of the plurality of pipeline phases, the third portion being execution phases, wherein the first functional unit comprises:

byte intermingling circuitry connected to receive a first source operand and a second source operand and having outputs connected to provide a destination operand in response to the control signals, wherein the byte intermingling circuitry is operable to treat the first and second operands each as a number N1 of ordered fields, such that the destination operand consists of a number N2 of fields selected from the N1 fields of the first source operand intermingled with a number N3 of fields selected from the N1 fields of the second source operand; and

wherein the first functional unit is operable to provide the destination operand intermingled in accordance to each of a set of byte intermingling instructions.

2. The digital system of Claim 1, wherein the byte intermingling circuitry is operable to receive the first source operand and second operand

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- 3. The digital system of Claim 1, wherein the byte intermingling circuitry is operable to provide a destination operand that consists of a N1-1 fields selected from the second operand and one field selected from the first source operand.
 - 4. The digital system of Claim 3, wherein the byte intermingling circuitry is operable the select a first N1-1 fields from a most significant portion of the second operand and to select a first field from a least significant portion of the first operand, such that the first field from the first operand is placed in a most significant portion of the destination operand, whereby a shift right and byte merge operation is performed.
 - 5. The digital system of Claim 4, wherein the byte intermingling circuitry is operable the select a second N1-1 fields from a least significant portion of the second operand and to select a second field from a most significant portion of the first operand, such that the second field from the first operand is placed in a least significant portion of the destination operand, whereby a shift left and byte merge operation is performed.
 - 6. The digital system of Claim 1, wherein the byte intermingling circuitry is operable to provide the destination operand by placing a most significant set of the N1 fields selected from the second operand in a most significant portion of the destination operand and by placing a least significant set of the N1 fields selected from the second operand in a most significant portion of the destination, whereby a byte swap operation is performed.

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- 7. The digital system of Claim 6, wherein the byte intermingling circuitry is operable to operable to provide the destination operand by placing a least significant set of the N1 fields selected from the second operand in a least significant portion of the destination operand and by placing a least significant set of the N1 fields selected from the second operand in a most significant portion of the destination, whereby a byte pack operation is performed.
- 8. The digital system of Claim 6, wherein the byte intermingling circuitry is operable to operable to provide the destination operand by placing a least significant one of the N1 fields selected from the second operand in a least significant portion of the destination operand and by placing a next to least significant one the N1 fields selected from the second operand in a most significant portion of the destination, whereby a byte unpack operation is performed.
- 9. The digital system of Claim 1, further comprising a register file connected to the first functional unit for providing the first and second source operands and connected to the first functional unit to receive the destination operand.
- 10. The digital system of Claim 1, wherein each of the set of byte intermingling instructions has a field for identifying a predicate register.

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11. The digital system of Claim 1 being a cellular telephone, further comprising:

an integrated keyboard connected to the CPU via a keyboard adapter; a display, connected to the CPU via a display adapter; radio frequency (RF) circuitry connected to the CPU; and an aerial connected to the RF circuitry.

12. A method of operating a digital system having a microprocessor a set of byte intermingling instruction, comprising the steps of:

fetching a first type of byte intermingling instruction for execution;

fetching a first source operand and a second operand selected by the first type of byte intermingling instruction;

treating the first and second source operands as a set of N1 fields;

intermingling selected ones of the N1 fields from the first operand and selected ones of the N1 fields from the second operand in a first selected order in accordance with the first type of byte intermingling instruction to form a first type of intermingled fields; and

writing a destination operand with the first type of intermingled fields.

13. The method of Claim 12, further comprising the steps of:
fetching a second type of byte intermingling instruction for execution;
fetching a first source operand and a second operand selected by the
second type of byte intermingling instruction;

treating the first and second source operands as a set of N1 fields;

intermingling selected ones of the N1 fields from the first operand and selected ones of the N1 fields from the second operand in a second selected order in accordance with the second type byte intermingling instruction to form a second type of intermingled fields; and

writing a destination operand with the second type of intermingled fields.

14. The method of Claim 11, wherein the step of intermingling isperformed during a single execution phase of the microprocessor.

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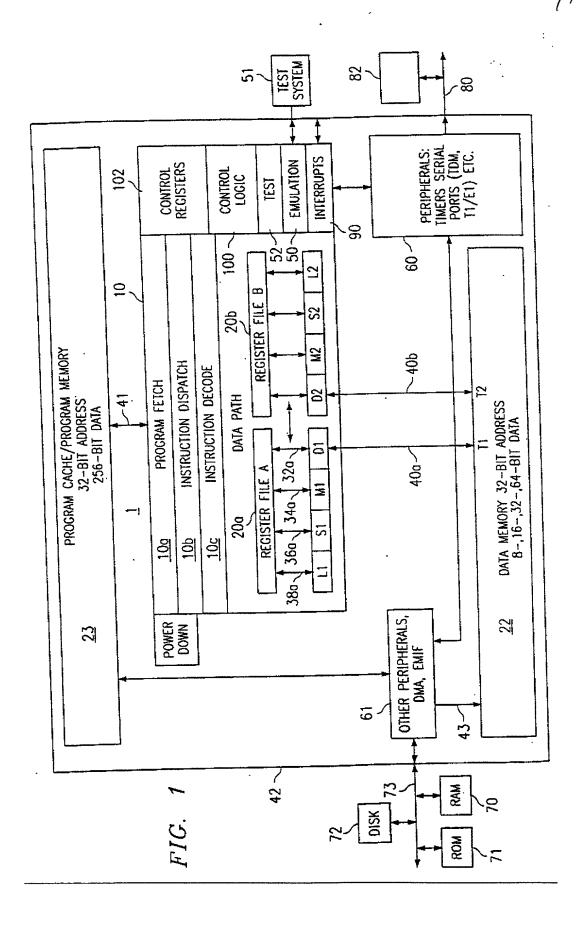
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ABSTRACT OF THE DISCLOSURE

A data processing system is provided with a digital signal processor that has a set of instructions for intermingling byte fields selected from a selected pair of source operands and storing the ordered result in a selected destination register. A first 32-bit operand (600) is treated as four 8-bit fields while a second 32-bit operand (602) is treated as four 8-bit fields. Intermingling circuitry 702 is operable to form an ordered result in accordance with each one of the set of byte intermingling instructions. An instruction is provided that performs a shift right and byte merge operation. Another instruction is provided that performs a shift left and byte merge operation. Another instruction is provided that perform a byte swap operation. A set of instructions are provided that perform various byte packing and unpacking operations.

Figure 6A-6L

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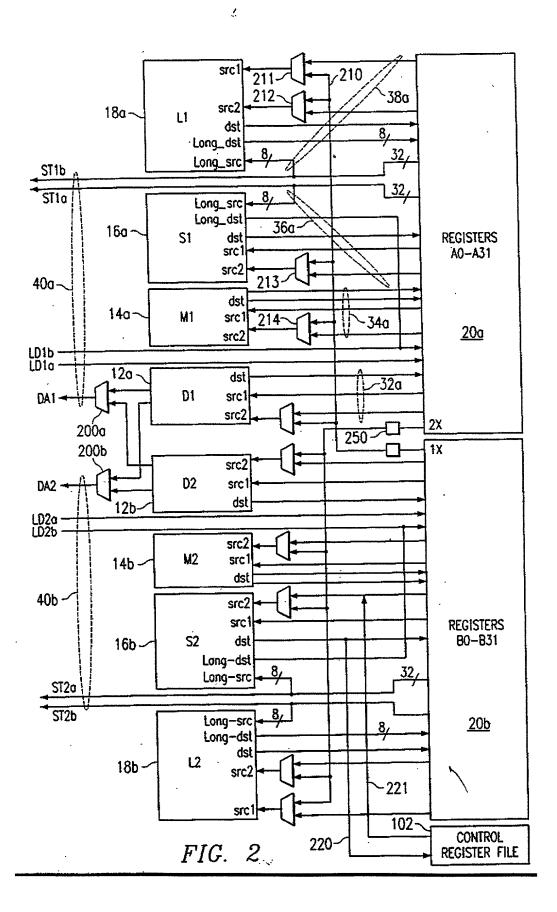


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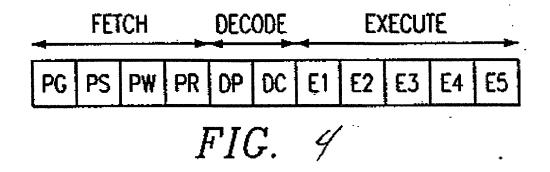
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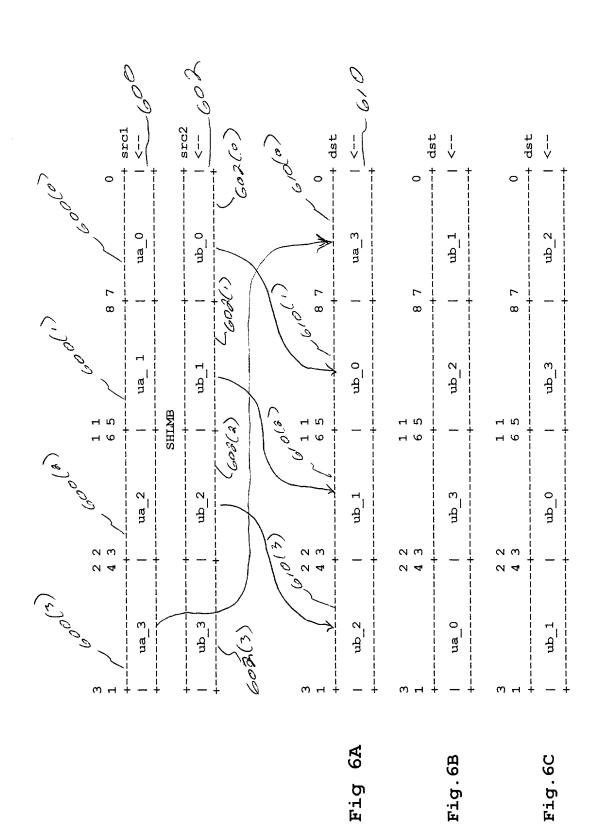
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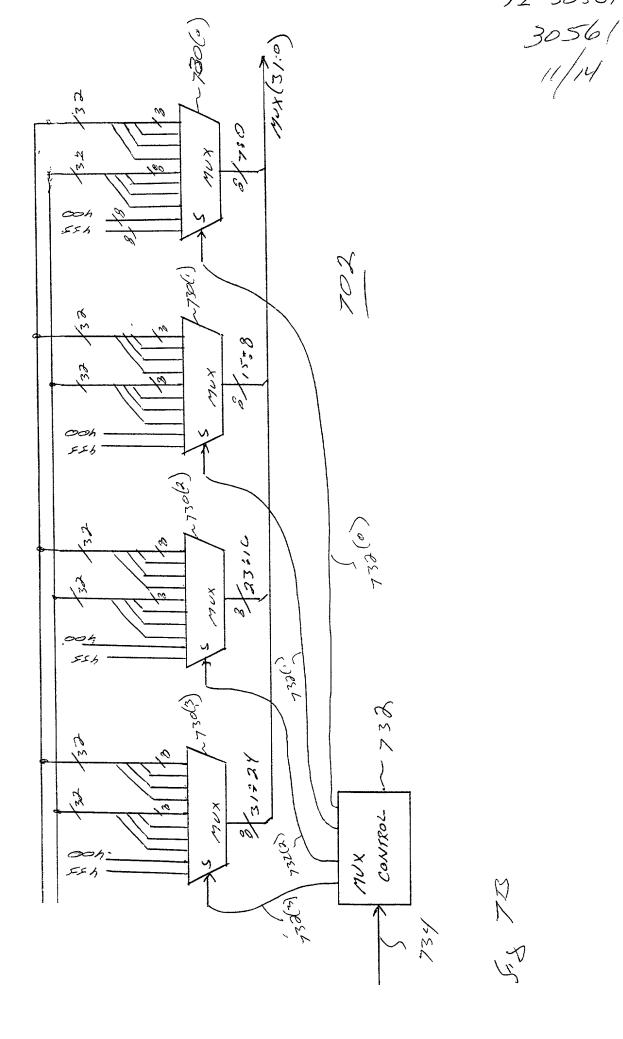


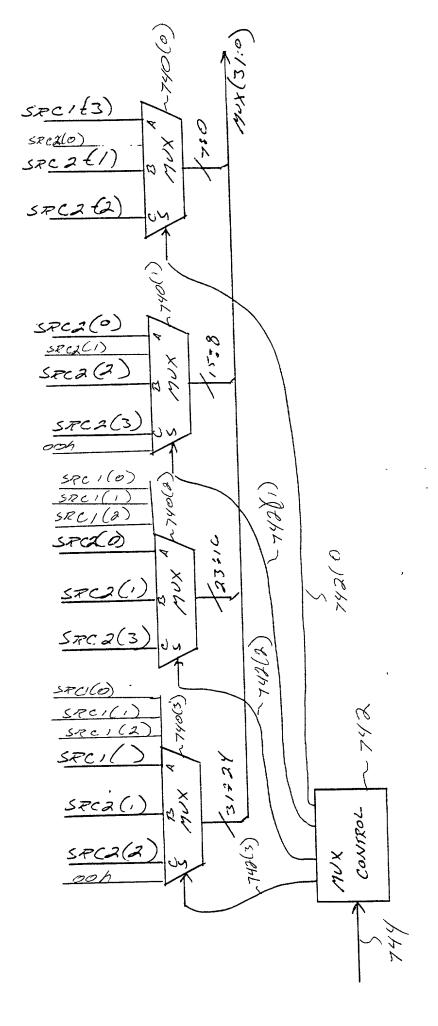
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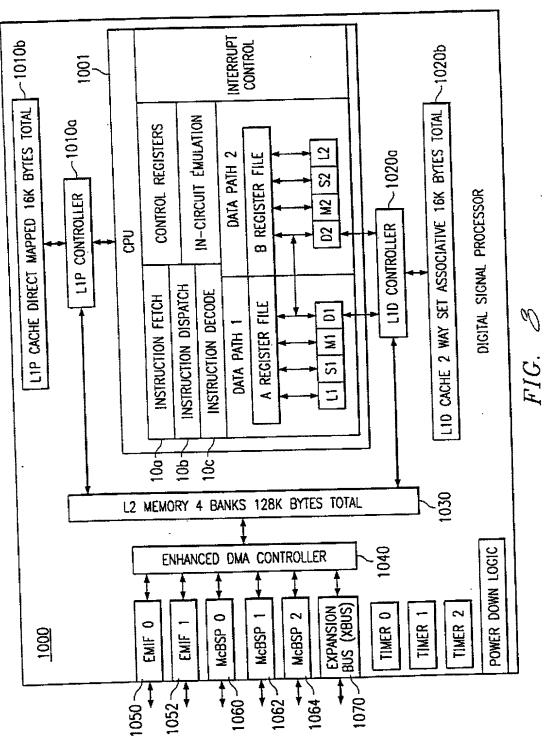
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PAGE 1 OF 1

APPLICATION FOR UNITED STATES PATENT DECLARATION AND POWER OF ATTORNEY

As a below named inventor, I declare that my residence, post office address and citizenship are as stated below next to my name; that I verily believe that I am the original, first and sole inventor if only one name is listed below, or an original, first and joint inventor if plural inventors are named below, of the subject matter which is claimed and for which a patent is sought on the invention entitled as set forth below, which is described in the attached specification [of Application Serial No. XX, filed XX]; that I have reviewed and understand the contents of the specification, including the claims, as amended by any amendment specifically referred to in the oath or declaration; that no application for patent or inventor's certificate on this invention has been filed by me or my legal representatives or assigns in any country foreign to the United States of America; and that I acknowledge my duty to disclose information which is material to the patentability of this application in accordance with Title 37, Code of Federal Regulations, Section 1.56;

I further declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true, and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under section 1001 of Title 18 of the United States Code, and that such willful false statements may jeopardize the validity of the application or any patent issuing thereon.

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TIFLE OF INVENTION:	essor Having a Set of Byte Intermingling In	structions
	NT THE FOLLOWING ATTORNEYS TO PROSE N THE PATENT AND TRADEMARK OFFICE CO	
Prac	ctitioners at Customer Number: 23	494
SEND CORRESPONDENCE TO:		DIRECT TELEPHONE CALLS TO:
Gerald E. Laws Texas Instruments Incorporated P.O. Box 655474, MS 3999 Dallas, TX 75265		Gerald E. Laws (972) 917-5287
NAME OF INVENTOR: (1)	NAME OF INVENTOR: (2)	NAME OF INVENTOR: (3)
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UK	India	UK
SIGNATURE OF INVENTOR:	SIGNATURE OF INVENTOR:	SIGNATURE OF INVENTOR:
DATE:	DATE:	DATE: